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Deep Neural Networks for the Calibration of Timing Detectors

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Time of arrival prediction

- » Diamond detectors (double diamond)
 - Devised and used in the CMS-PPS system, at the LHC (CERN).
- » A particle flying through a detector triggers a voltage peak.
- » A sampling device produces a sampled time series of voltage.
- » Measurement goal: find the timestamp of a particle.
- » Project goal: estimate the performance of neural networks with respect to the method used currently.



Example time series from a diamond detector

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Time walk effect

- » Easiest algorithm to compute the time of arrival: constant threshold
 - Disadvantage: prone to the time walk effect



Example of the time walk effect. Although both signals reach their maximum at the same time, the threshold-crossing time is different.



Constant Fraction Discriminator

- » The CFD algorithm (Constant Fraction Discriminator)
 - Method used currently at the LHC
 - Goal: mitigation of the time walk effect
 - Implemented as the normalised threshold algorithm preceded by the baseline subtraction



The CFD algorithm. Left: (0) before normalisation, (1) baseline subtraction, (2) division by maximum. Right: after the normalisation the timestamp can be found using the fixed threshold algorithm



Dataset

- » Data acquired in 2020 in the test beam facility at the DESY-II synchrotron.
- » Diamond detectors mounted together with much more precise MCP detectors
 - Expected diamond detector precision: 50-100 ps
 - Expected MCP precision: ~10 ps
- » We used only the events where a particle was detected both by the diamond detector and MCP.
- » The true timestamps (ground-truth) are based on the MCP signals.
- » Training goal: minimise the difference between the predicted and ground-truth timestamps given a time series from the diamond detector.



Dataset example. Left: an MCP signal with marked ground-truth timestamp. Right: a signal from a diamond detector; red: the ground-truth timestamp (includes the t_0 shift of both signals), green: the CFD timestamps computed on the diamond detector time series (used to compare the neural networks with CFD).



Neural networks

- » Tested architectures
 - Multilayer Perceptron (MLP)
 - Regular Convolutional Neural Network (CNN)
 - UNet-based network
- » Model selection done using a two-step hyperparameter tuning procedure.
 - 1. Find top five models using **keras-tuner** (a Python framework for TensorFlow)
 - 2. Use the cross-validation to find the optimal model.
- » Following hyperparameters were optimised:
 - network depth,
 - number of neurons (dense layers), number of filters (convolutional layers),
 - batch normalisation application,
 - dropout (dense layers) or spatial dropout (convolutional layers) usage.



Precision assessment method

- » Comparison with the "reference" detector – MCP
 - For each measurement: calculate the difference between the diamond det. and MCP.
 - Precision metric: std of differences
- » A Gaussian can be fitted to the data to reduce the impact of outliers.
 - Precision metric: std of a Gaussian fitted to the difference histogram





Optimal model selection

» Precision statistics computed through a cross-validation of the optimal models

architecture	mean [ps]	std [ps]
MLP	63.9	0.9
CNN	62.8	1.3
UNet	60.7	1.2

» The best (smallest) precision: UNet



- » Symmetric parts: encoder and decoder
- » Both the encoder and the decoder contain two blocks.
 - Each block: three convolutional layers before a MaxPooling layer.
- » Number of filters increases with consecutive blocks.
- » Applied batch normalisation and spatial dropout (rate: 0.1)



Results

- » Final results obtained with the **test dataset** not used in the previous tests
- » Precision comparison with CFD:

CFD	NN	Improvement
71.6 ps	59.4 ps	17.0%

- » Results for the signals trimmed to 24 samples:
 - The same length as at the LHC

CFD	NN	Improvement
73.3 ps	62.1 ps	15.3%

- » The tests above were run on a single detector channel (diamond sensor).
 - The improvements for other channels range from 8% to 23%.

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The end

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